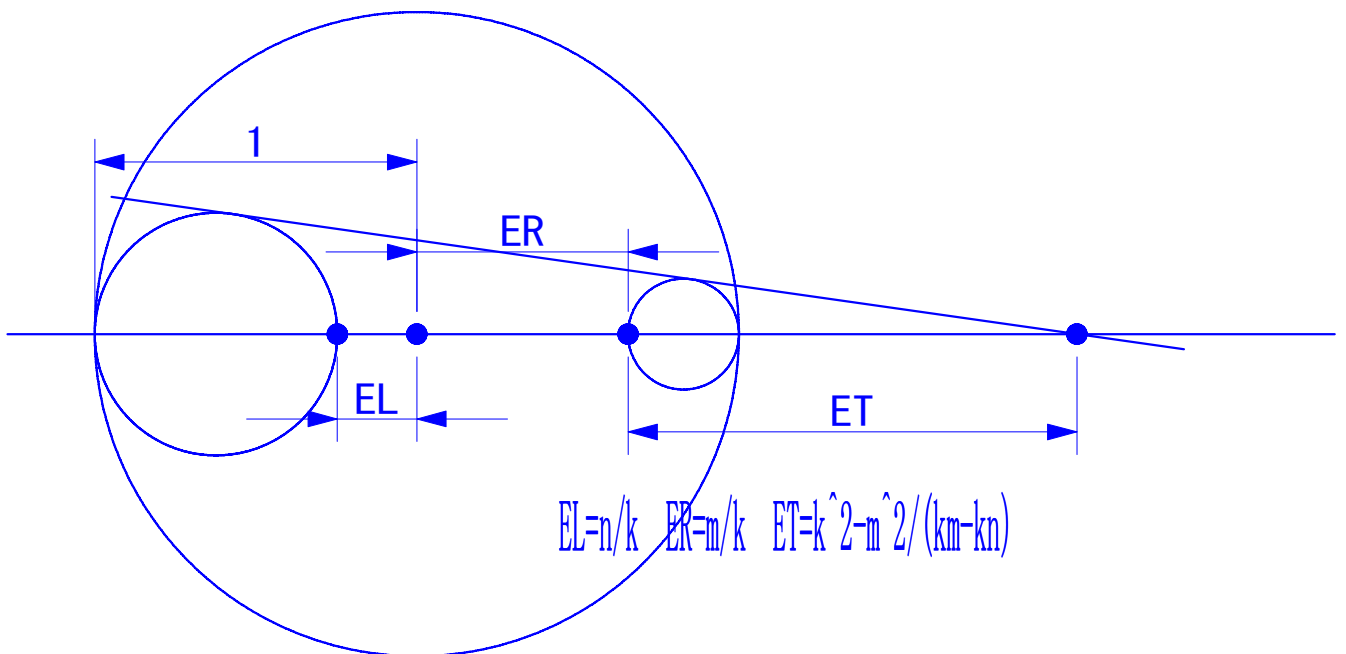


# DOVALINOUTの3焦点

$$mR1 \pm nR2 = kC$$



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